



Heavy-Duty Drivelines

The AVL HD E-Axle Technology Showcase

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Today's Presenters



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Today's Agenda

- 1 About AVL**
- 2 Introduction and Target Setting**
- 3 System Development**
- 4 Hardware Validation**
- 5 Production Adaptions**
- 6 Q&A**



About AVL



Reimagining Motion

“We are driven by a **passion** to examine the science, mechanics and philosophy of movement. To help create a world that is climate-neutral and one that makes **safe, comfortable, green mobility** a reality for everyone.”

Helmut O. List

Chairman and CEO
AVL List GmbH

AVL at a Glance



1948

Founded



29

Countries
Represented



12,200

Employees Worldwide



10 %

Of Turnover Invested
in Inhouse R&D

75+

Years of Experience

50+

Global Tech and
Engineering Centers

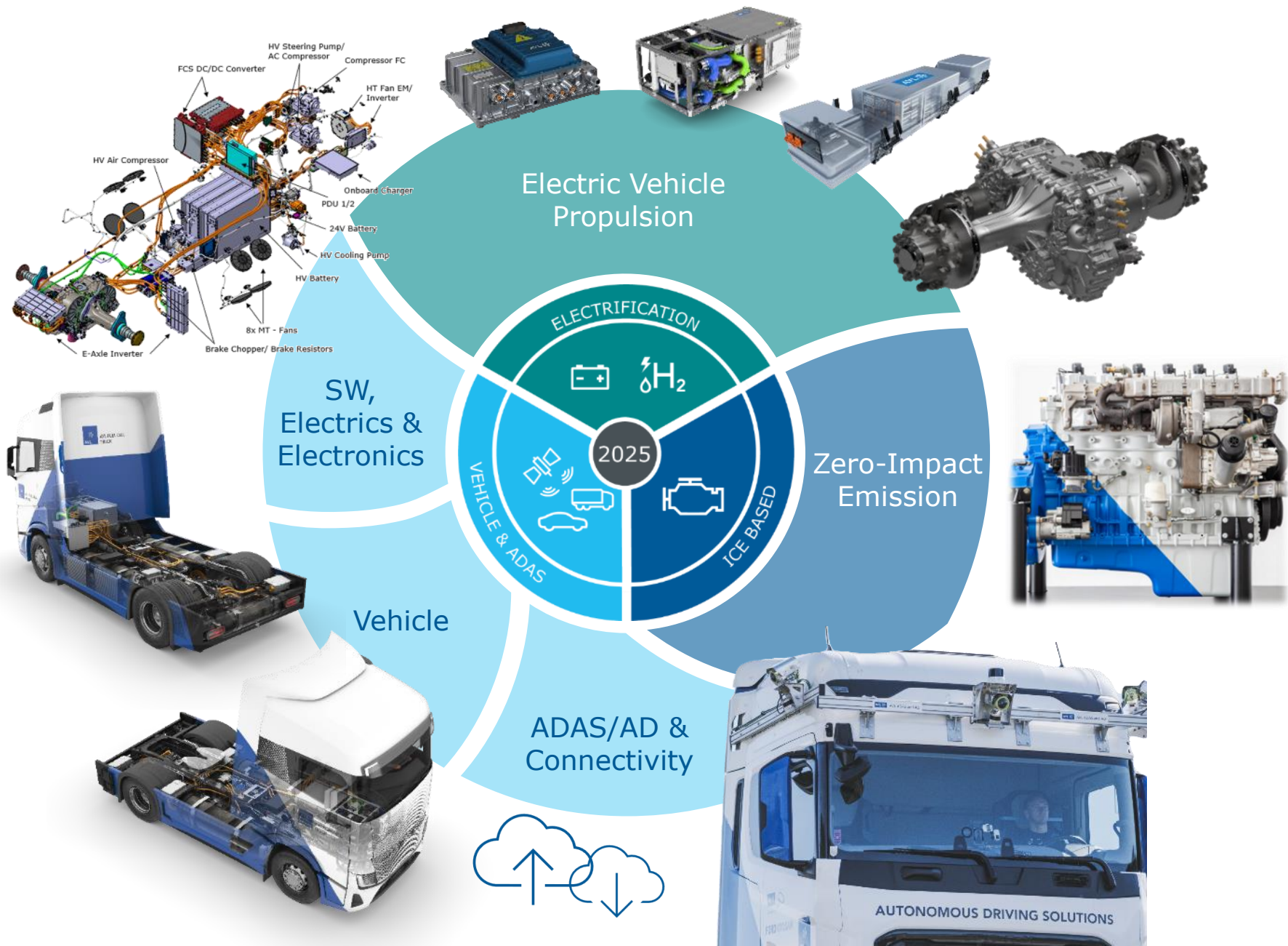
68 %

Engineers and
Scientists

2,200

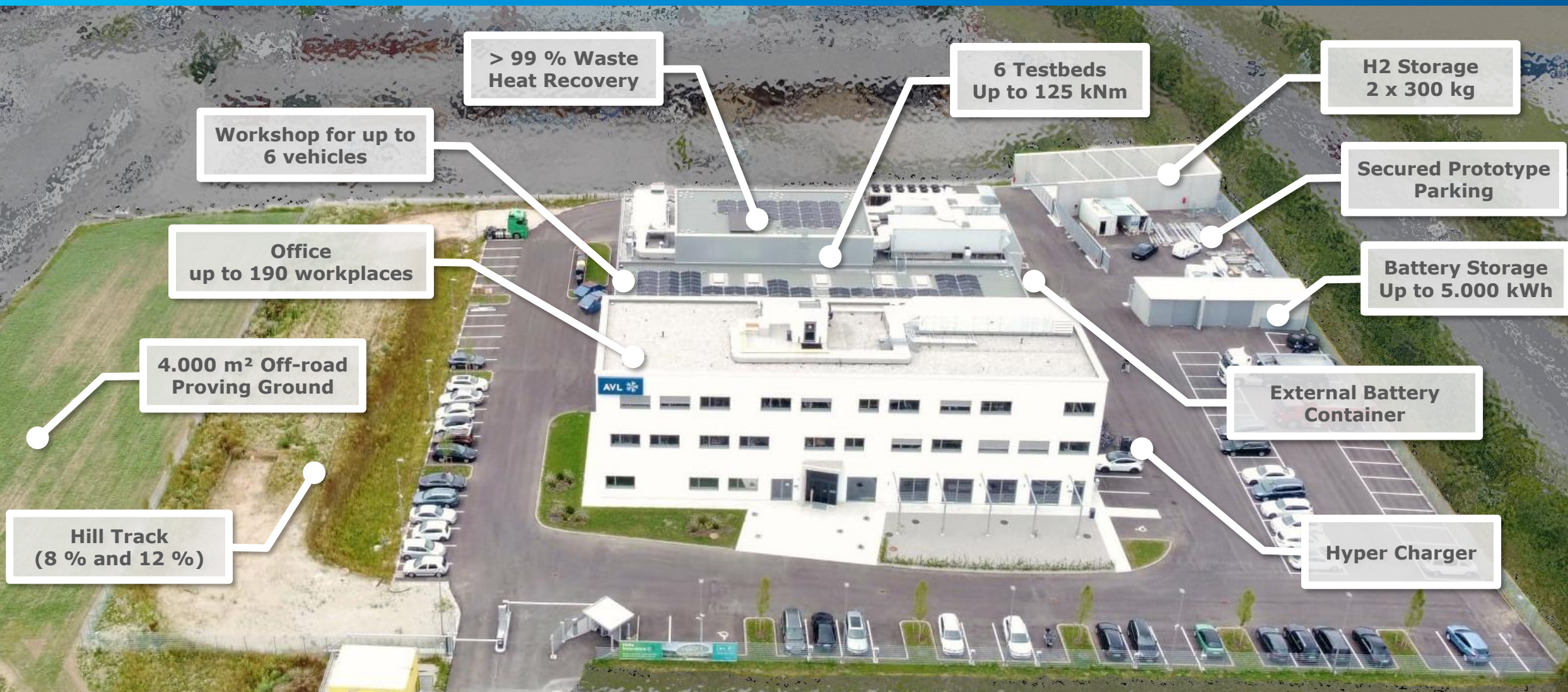
Granted Patents
in Force

Truck & Bus Focus Areas



New Tech-Center @Steyr

Total Area of 15.000 m² focused on Flexibility and Multi-Use





Introduction and Target Setting

Challenges



Legislative targets will demand ZEV for all CVs. e-Axles are demanded for compliance with regulatory limits and policy initiatives



Packaging space for batteries and H₂ tanks needs a holistic e-Axle development approach to ensure a compact e-axle structure



Integrated e-Axles come with high investment costs – Modularity and vehicle segments with high sales numbers are key



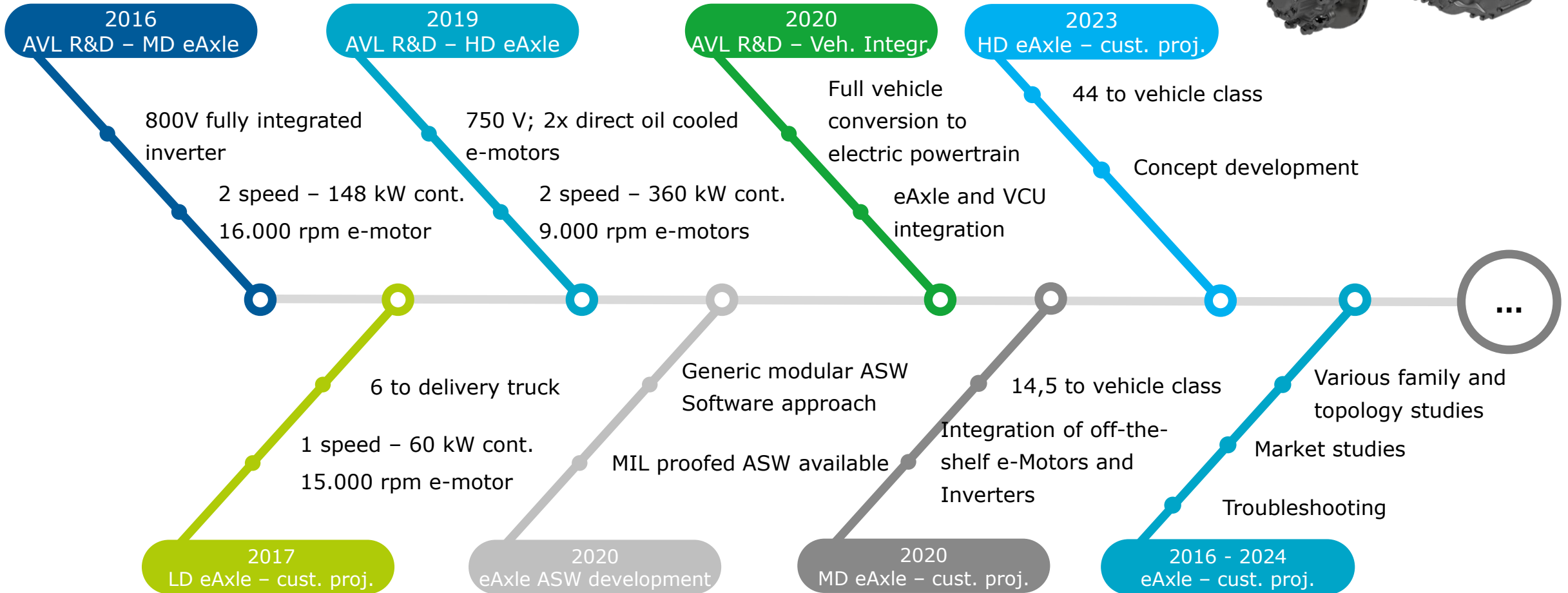
Specific OEM needs will require customized engineering solutions

- Fleet structure
- Time to market

Introduction



AVL Is a One-Stop Solution Provider for e-Axles in All Vehicle Classes

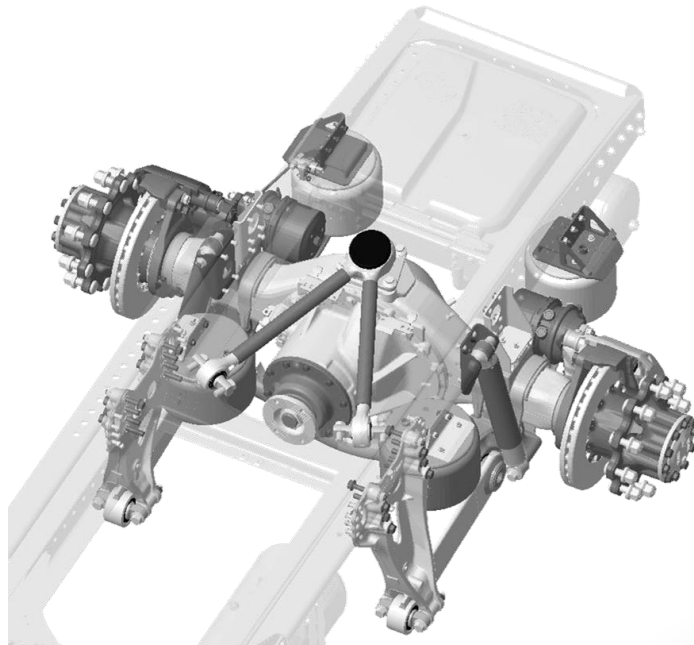
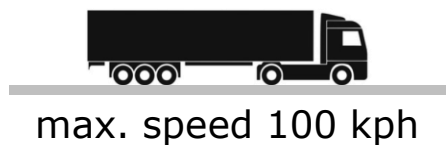
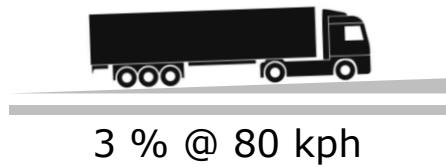
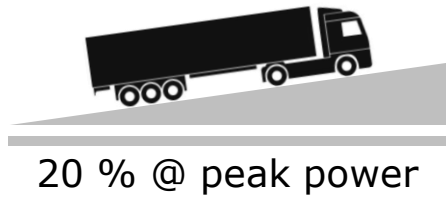


Introduction

Target Setting

Main Vehicle Performance Parameters

- Derived from real drive cycle (4x2 Truck)
- Required continuous power: **400 kW**



Conventional Axle Packaging

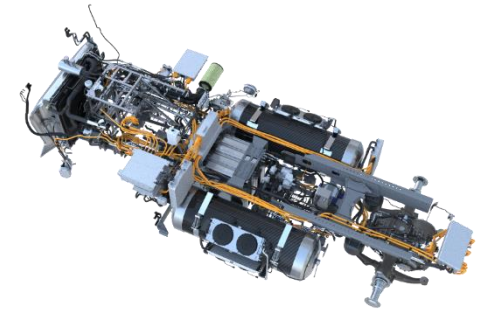




System Development

Multistep Workflow

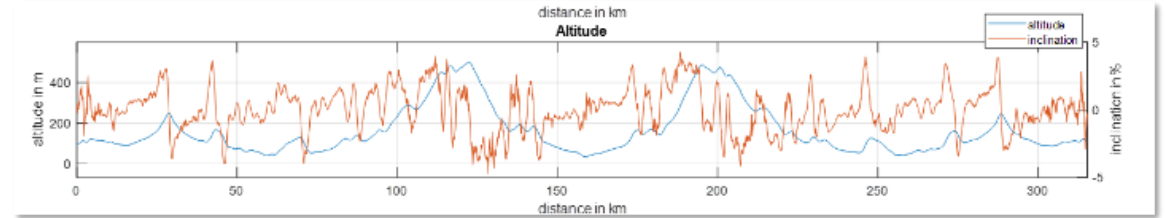
Example Powertrain Sizing



Static rough dimensioning according key requirements

e.g.: 2 % grade @ 80 kph

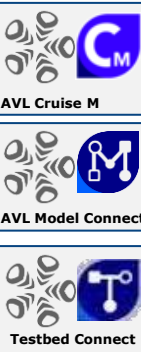
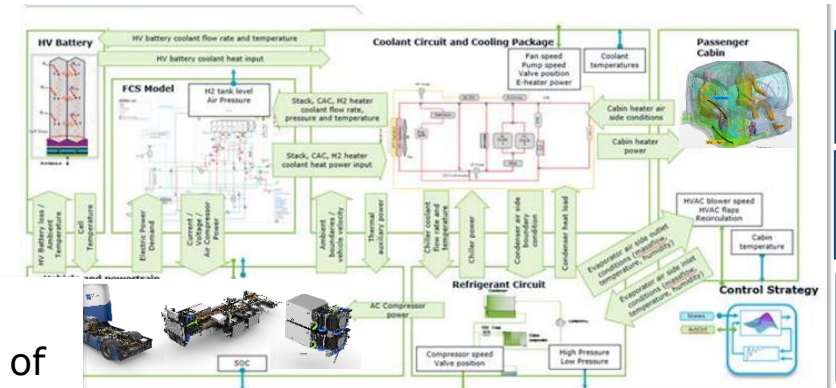
Mechanical drive power



Dynamic dimensioning according driving cycle

e.g.: Graz -> Wiener Neustadt -> Graz

Power split for battery and fuel cell



Plant model generation

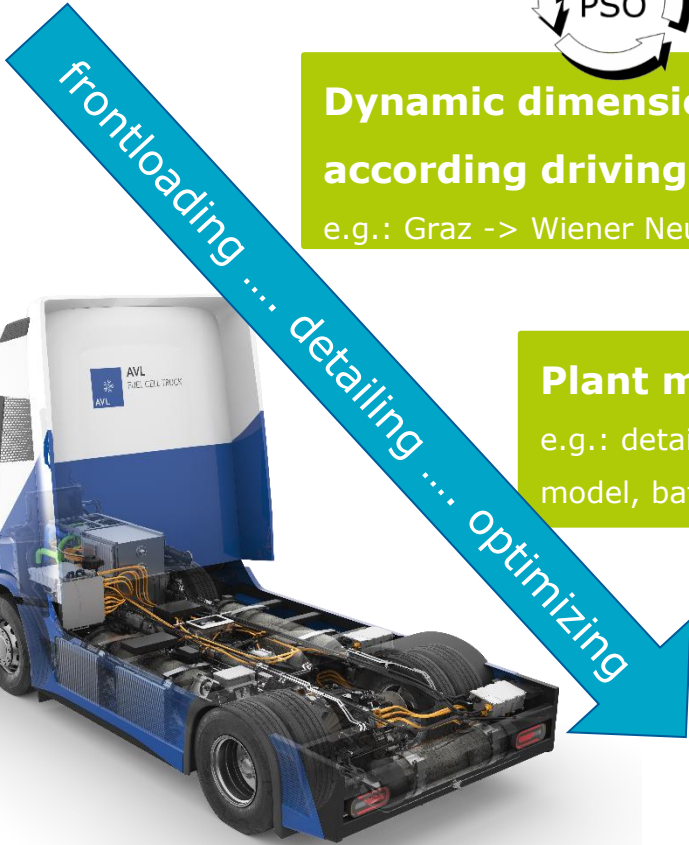
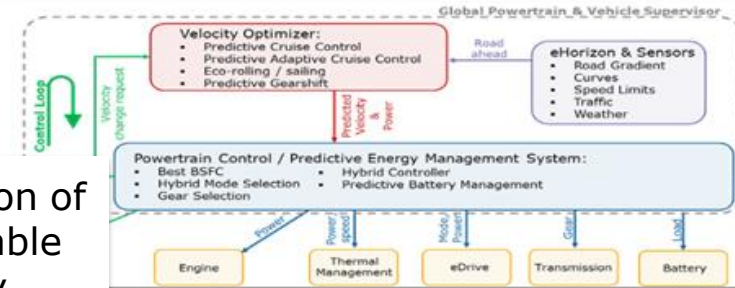
e.g.: detailed VTMS Model, detailed FCS model, battery model, ageing, ...

Detailed evaluation of limitations

Model enhancement

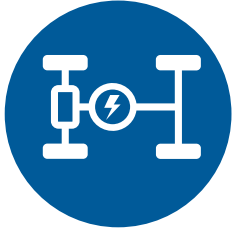
e.g.: Predictive Energy Management

Optimization of the available energy

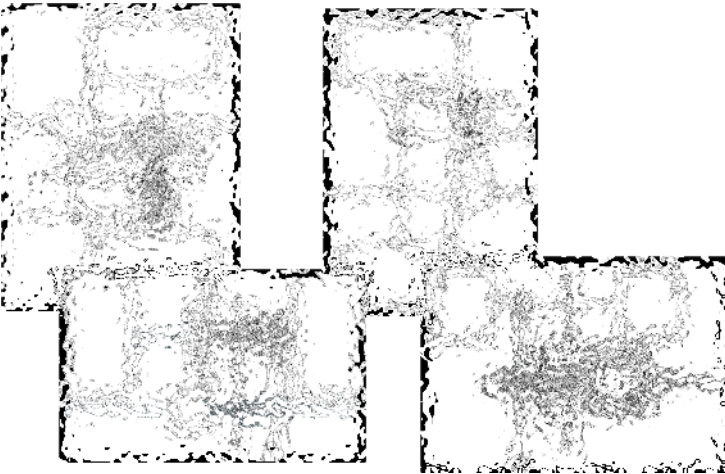


Utilizing Pso for Finding the Right e-Axle Topology

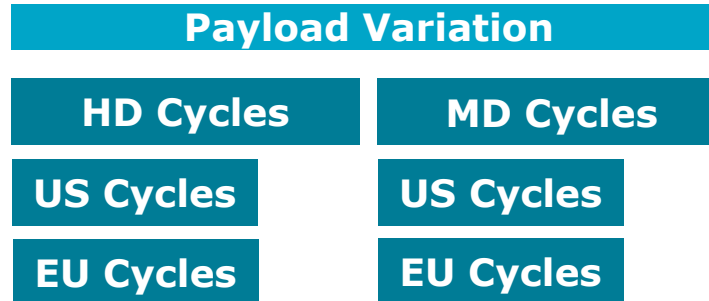
Input Data



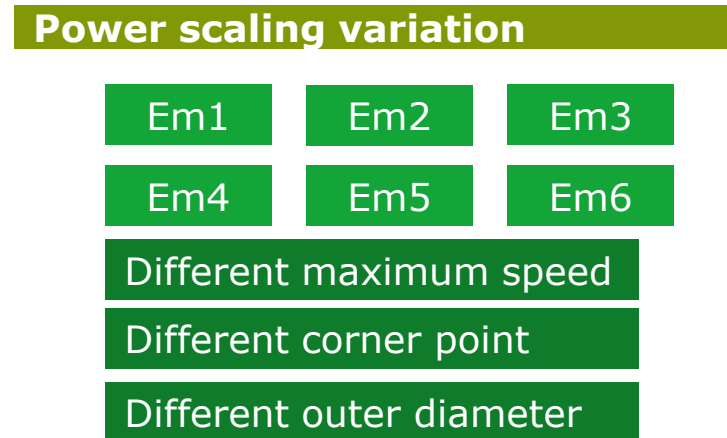
Different e-axes with different ratio families. Ratio variation within each family concept.



Different driving cycles (combination from EU + US) with different payloads.

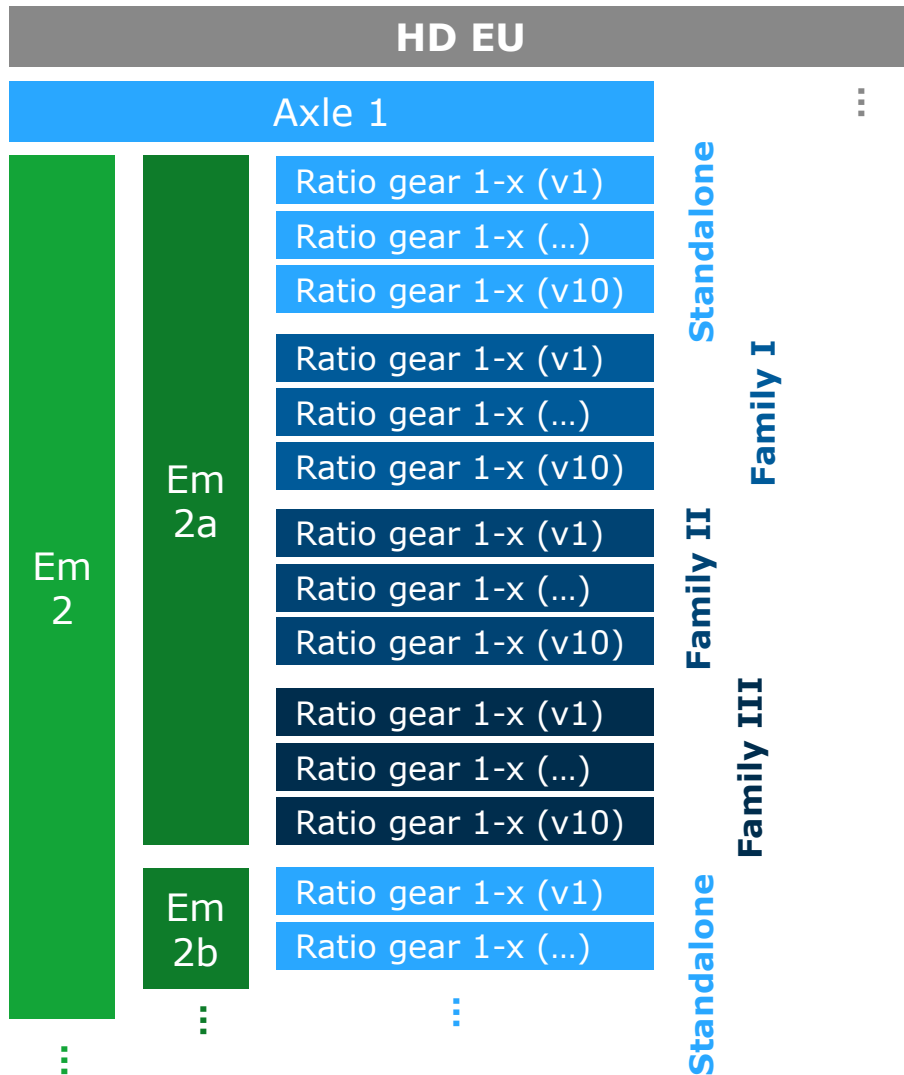


Different e-motor concepts with three different diameters each. Scaling of e-motor power.



Utilizing Pso for Finding the Right e-Axle Topology

Simulation matrix



Explanation of variations

- Each of the axles has different ratio variations
 - Standalone
 - Family I – family III
- Each axle and ratio variation is combined with the different e-motors
 - E-motor with same power, but different outer diameter
- Furthermore, each e-motor (with the different outer diameters) is also scaled in power

Resulting number of overall calculated variants

	Drive cycles	E-axle Topologies	E-motor types (average)	E-motor power scaling	E-motor diameters	Gear ratios (average)	Gear ratio families	Overall variants
	14	5	2	3	3	~10	4	
Overall	x	x	x	x	x	x	x	~50000
Per e-axle			x	x	x	x	x	~720
Per application		x	x	x	x	x	x	~3600
Explanation	<ul style="list-style-type: none"> HD MD EU US 	<ul style="list-style-type: none"> Axle 1 Axle 2 Axle 3 Axle 4 Axle 5 	<ul style="list-style-type: none"> Em1 Em2 Em3 Em4 Em5 Em6 	<ul style="list-style-type: none"> +0 % +10 % +20 % 	<ul style="list-style-type: none"> 123 mm (a) 456 mm (b) 789 mm (c) 	<ul style="list-style-type: none"> Ratio gear 1-x (v1) Ratio gear 1-x (...) Ratio gear 1-x (v10) 	<ul style="list-style-type: none"> Standalone Family I Family II Family III 	

Utilizing Pso for Finding the Right e-Axle Topology

KPI Post-Processing via Matlab App

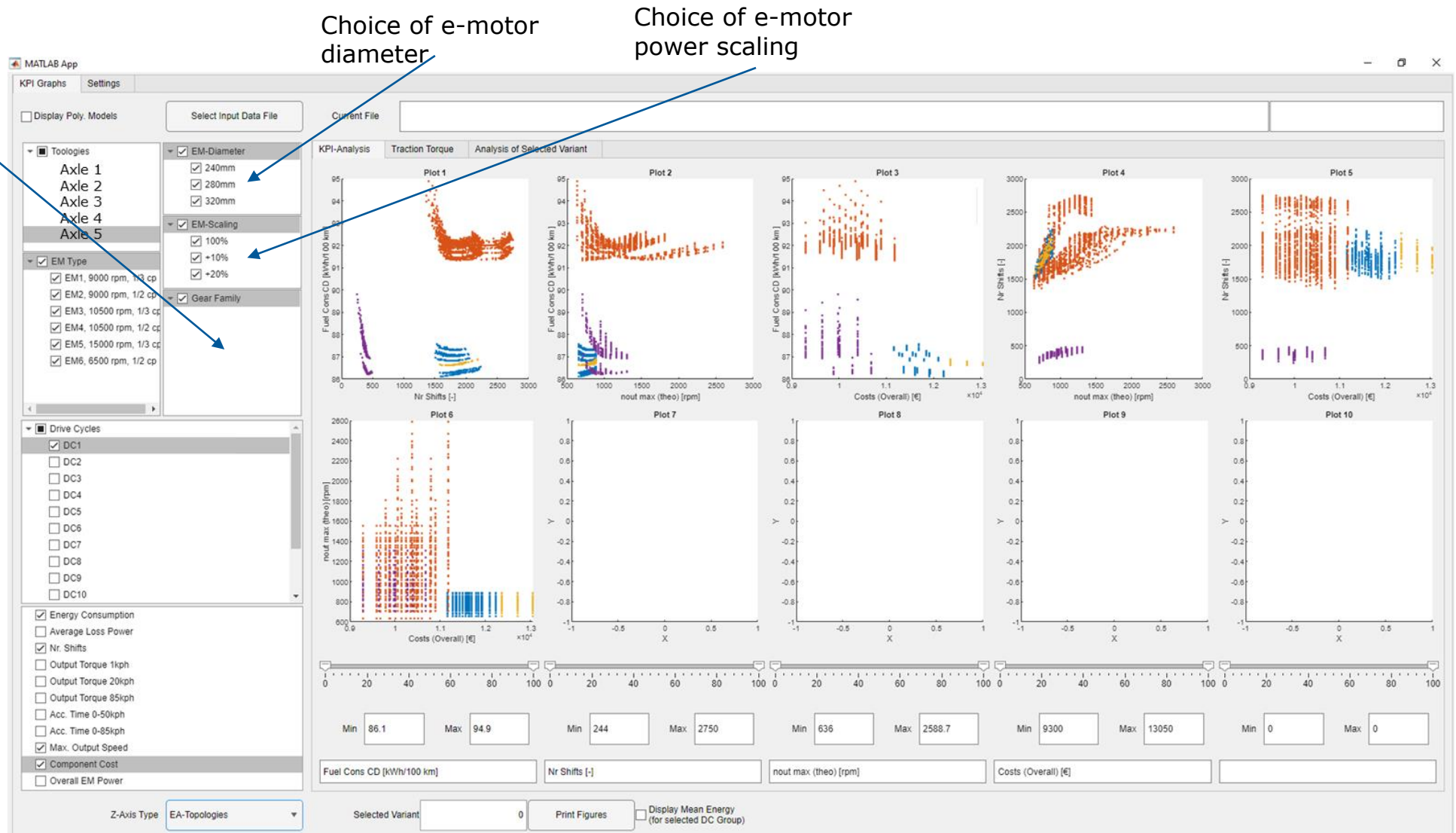
Choice of gear family

Choice of axle

Choice of e-motor type

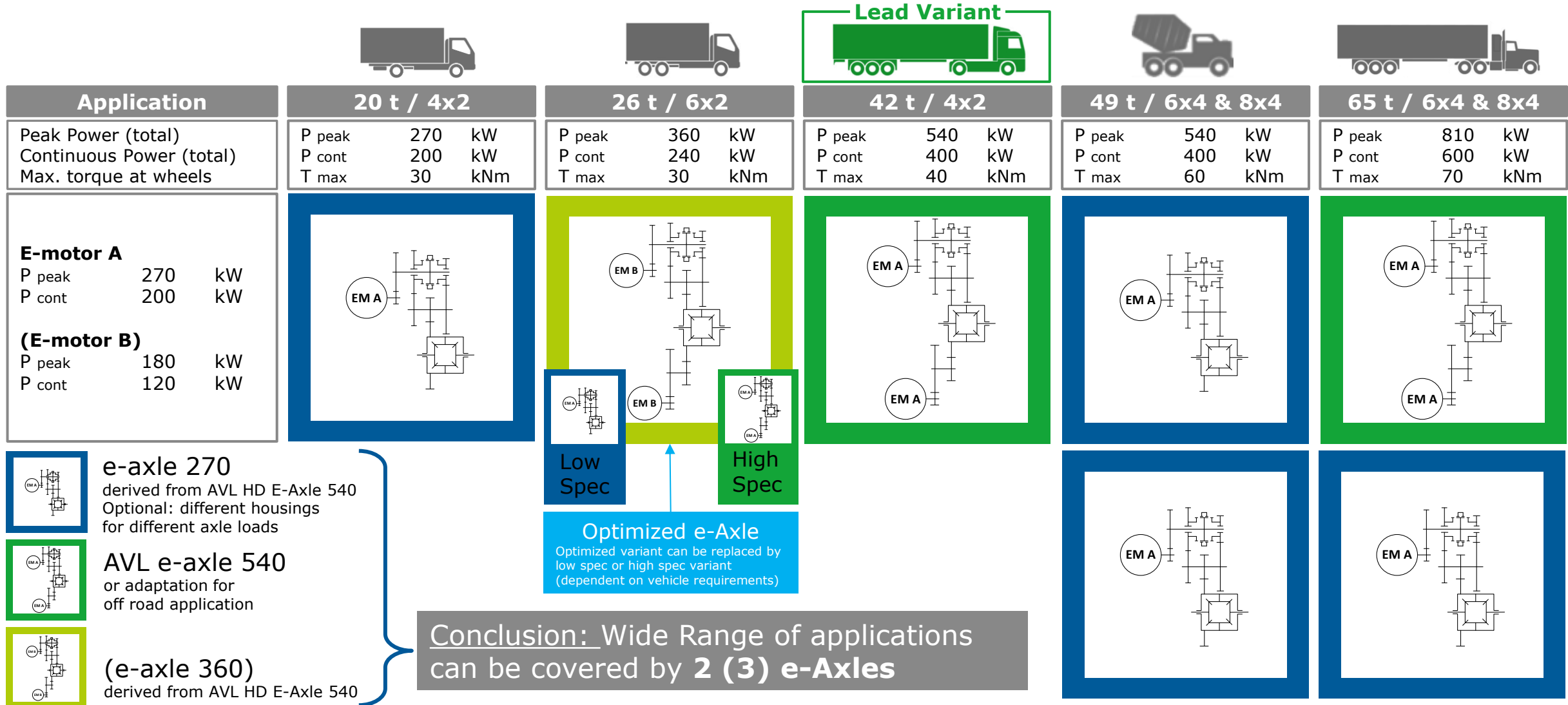
Choice of drive cycle

Choice of KPIs

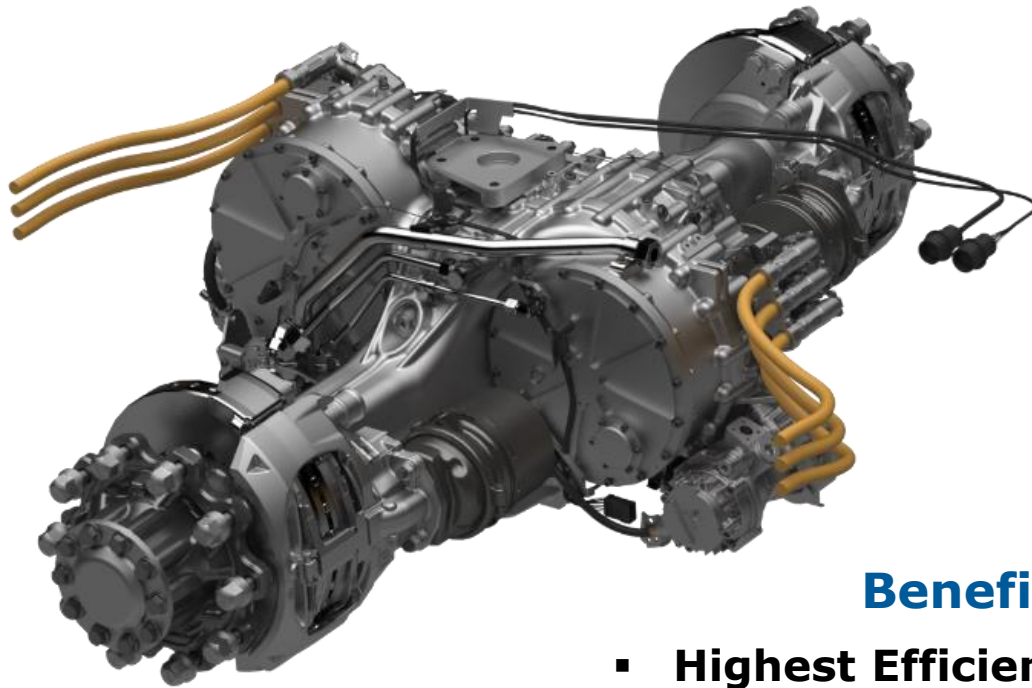


AVL HD e-Axle Development

Modularity Example (MD to HD)



AVL HD e-Axle Development Technology Demonstrator (A-Sample)



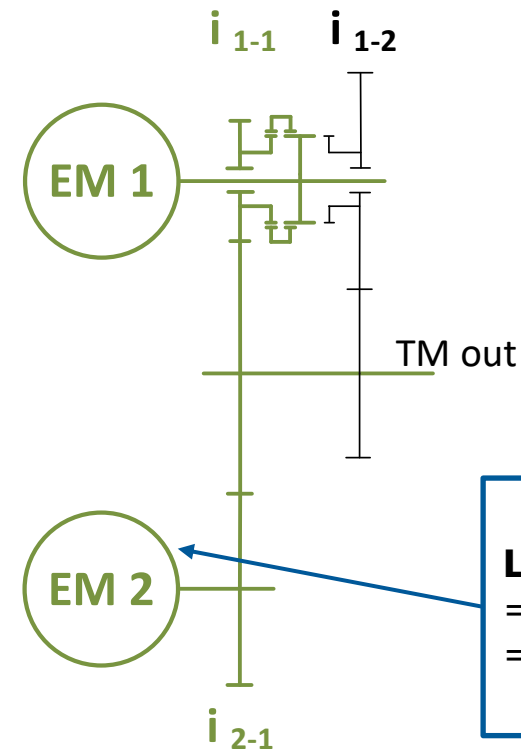
* without brakes

Benefits:

- Highest Efficiency
- Weight < 1.000 kg*
- Powershift Functionality
- Flexible, Scalable and Modular Architecture

E-motors (PSM)

- 2 x 270 kW peak power
- 2 x 200 kW continuous power
- 9.000 rpm max. rotational speed
- Direct oil cooling for highest torque density



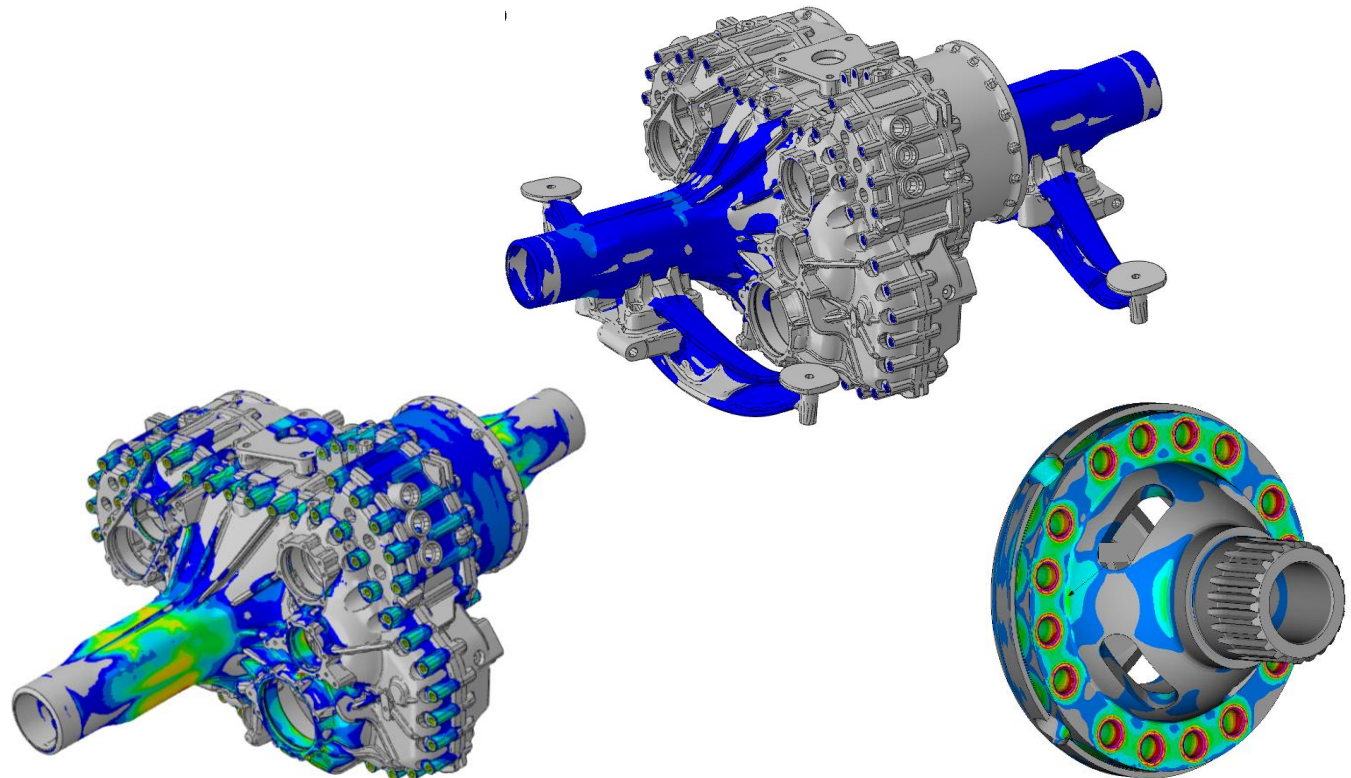
Long Haul Drive Cycle
=> 70 % EM2
= high efficiency

AVL HD e-Axle development

FEA Simulations

Strength and lifetime of housings, chassis parts and other e-axle components
(e.g. differential case, planetary carrier)

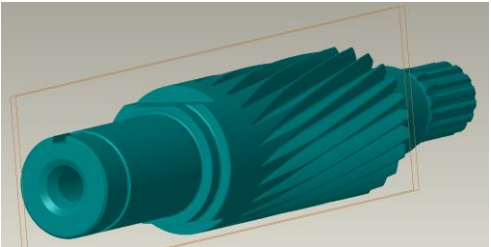
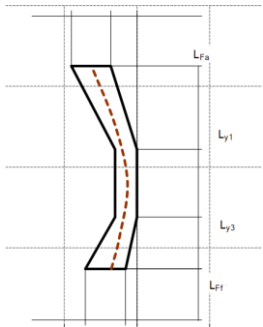
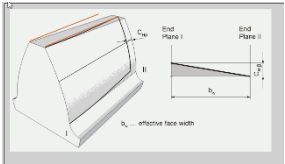
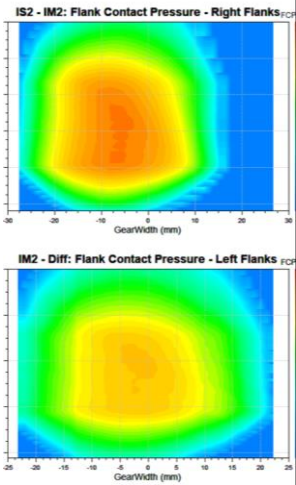
- Various load cases to ensure **structural strength and lifetime** of e-axle and chassis components
 - Static loads
 - Dynamic loads
 - Torque loads
 - Combined loads
- Check of **bolt connections**
- Check of **flange tightness**
- Input for NVH and CFD simulations



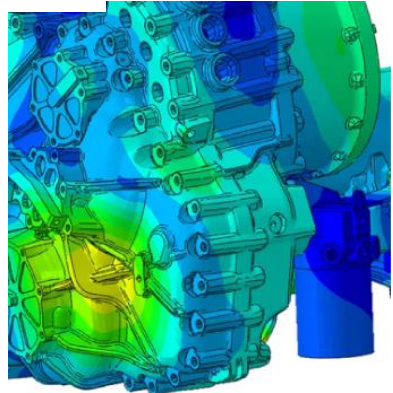
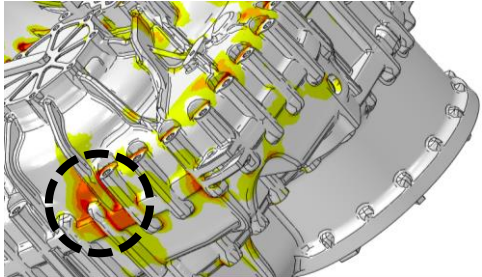
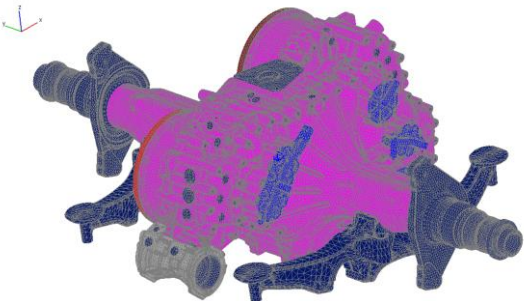
AVL HD e-Axle Development

NVH Optimization

Optimization of gear micro geometry (contact pattern)



Reduction of structure born noise

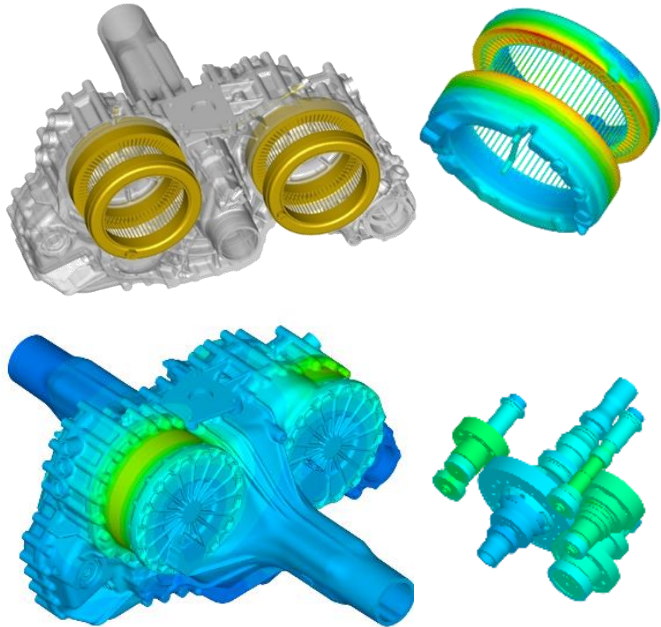


AVL HD e-Axle Development

Simulations for Cooling and Lubrication System

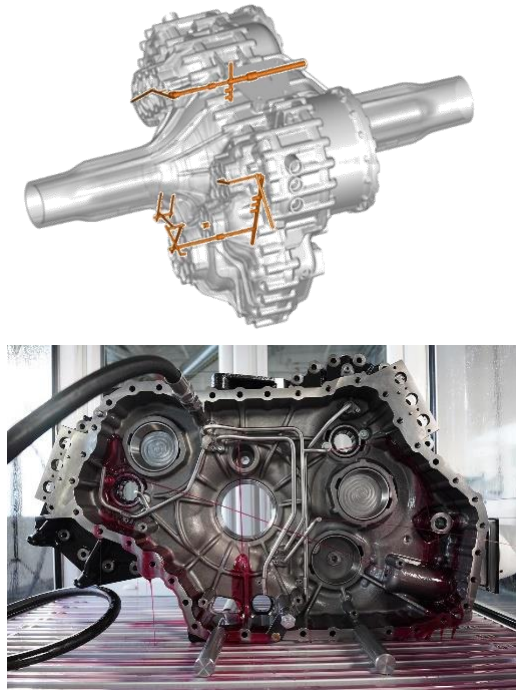
Cooling system

- Simulation of temperature distribution
- Highly efficient direct oil cooling system for high continuous e-motor power
- No overheating of oil and components for high lifetime & short maintenance intervals



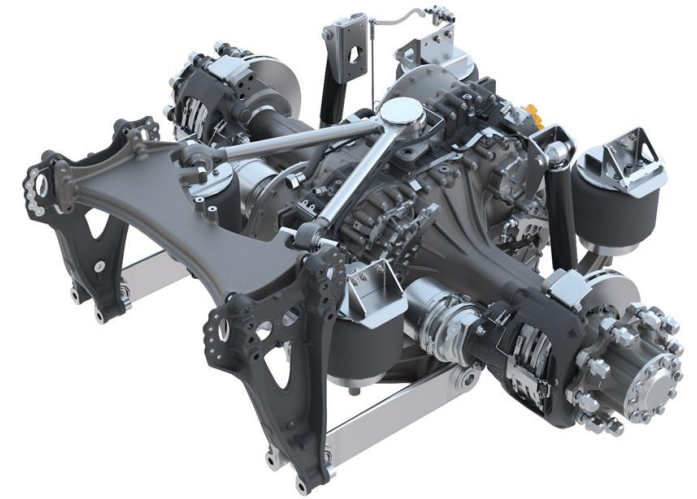
Lubrication of transmission components

- Simulation of oil distribution
- Validation on test rig
- Defined lubrication oil flows to transmission components for high reliability and durability



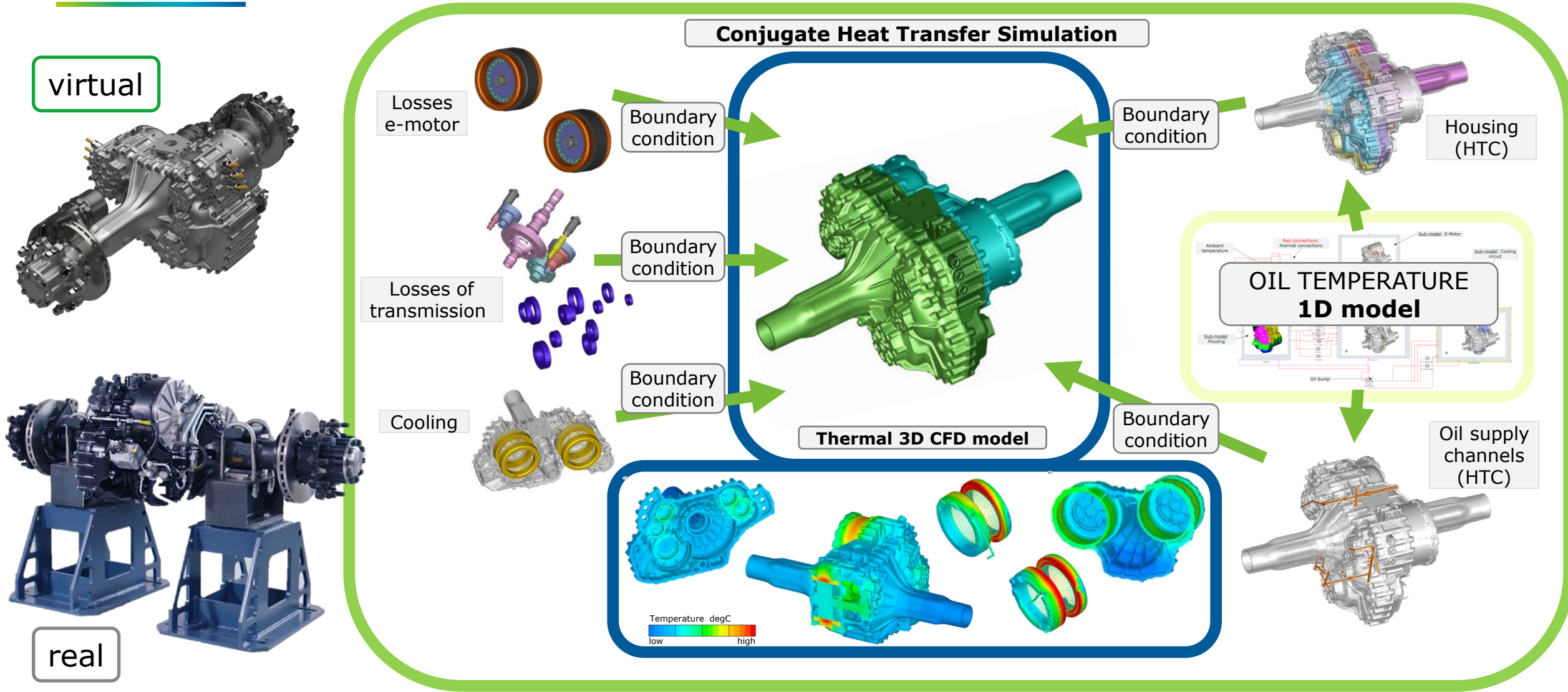
Integration in vehicle

- 3D CFD underhood simulation of heat transfer in installed condition
- Reliable cooling system in real working conditions



AVL HD e-Axle Development

Thermal Virtual Validation

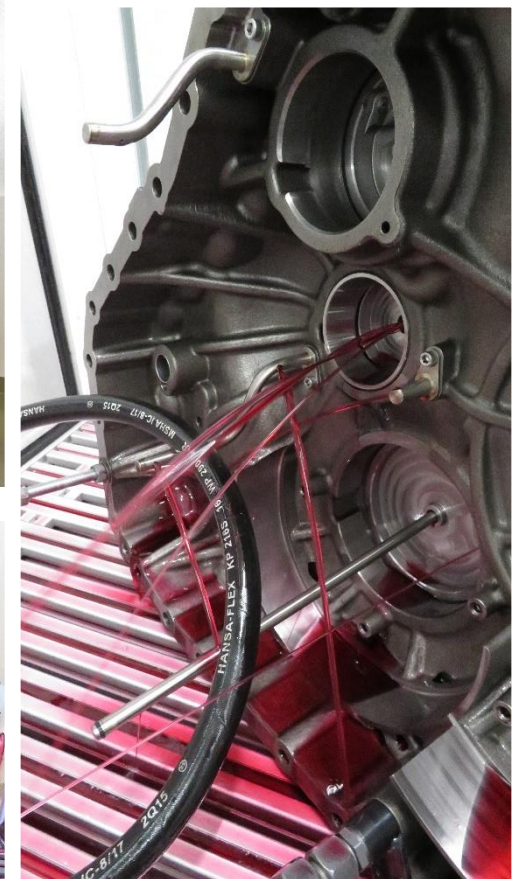
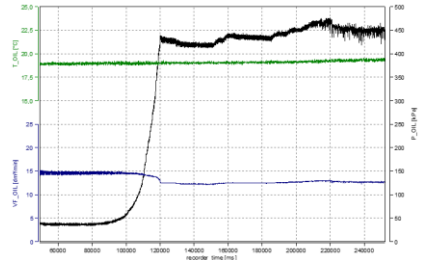
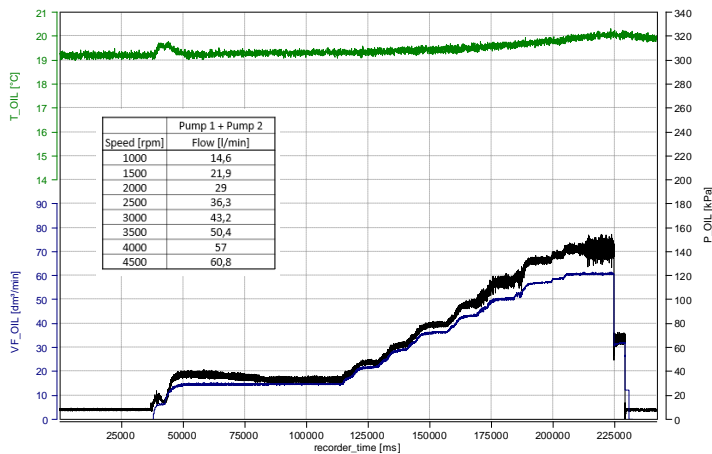




Hardware Validation

AVL HD e-Axle Development Lubrication Test

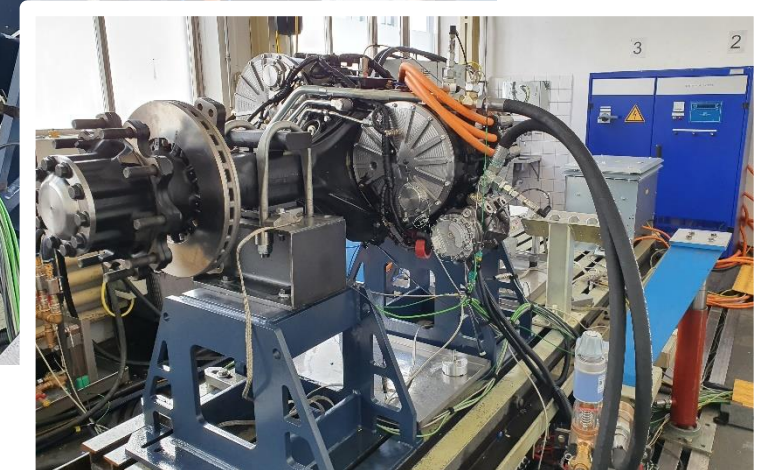
- Oil distribution test
- Pump performance test
- Pressure relive valve adjustment / function test
- Delta p measurements



AVL HD e-Axle Development

Basic Function Test – No Load

- Resolver adjustment
- Inverter measurements
- E-Motor measurements
- Parameter check
- SW Check
- Shifting function check



AVL HD e-Axle Development

Basic Function Test – Under Load

- Shifting behavior measurement
- Resolver adjustment
- Inverter measurements
- Temperature behavior (E-Motor, Inverter, System)
- Run in
- SW adjustments / checks



AVL HD e-Axle Development

Contact Pattern Test

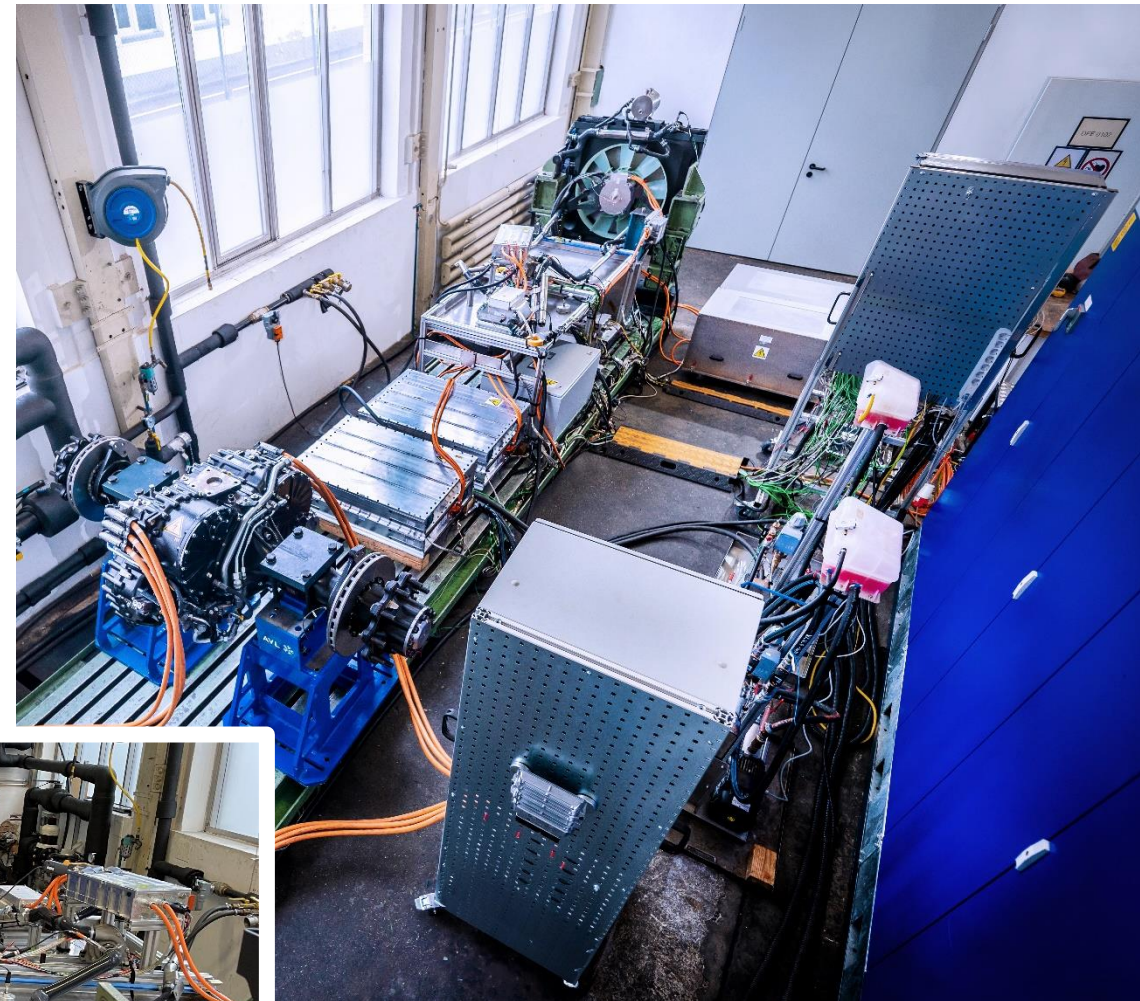
- At nominal torque (all gears, pull and coast)
- At peak torque (all gears, pull and coast)



AVL HD e-Axle Development

Vehicle Integration Tests

- Batterie tests
- E-Axle tests
- E-Motor/Inverter tests
- Thermal / cooling performance tests
- EMC pre-tests
- SW tests
- Communication tests
- Fault injection testing

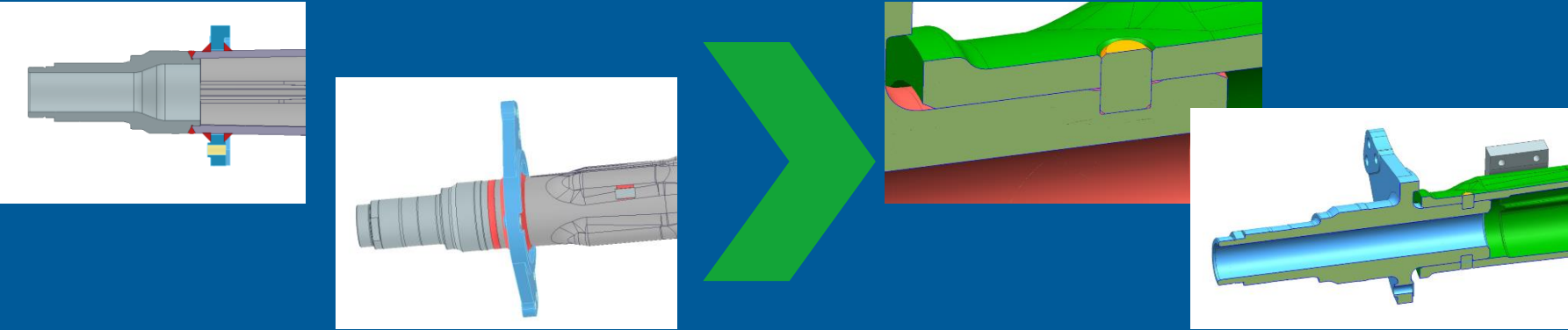




Production Adaptations

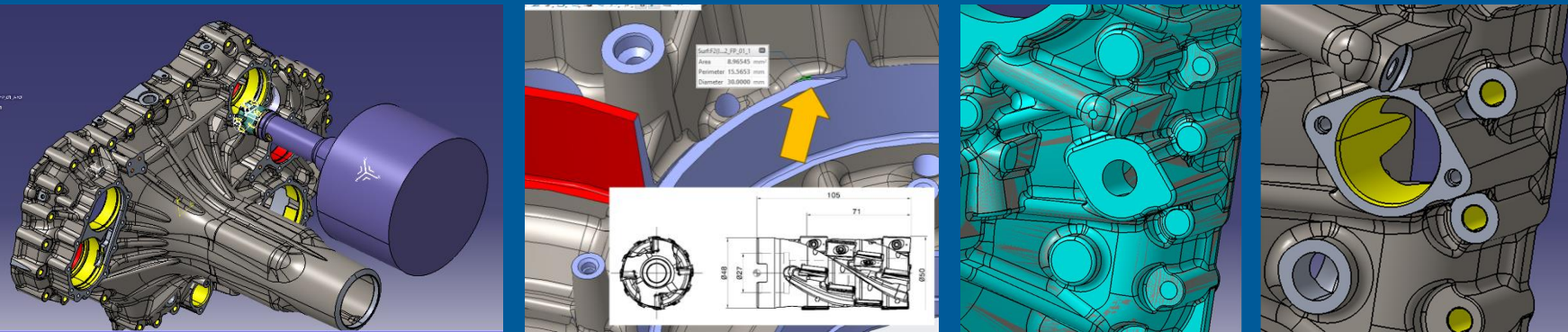
AVL HD e-Axle Development

Adaptations for Production



The diagram illustrates a design change. On the left, a grey cylindrical component is shown with a blue bracket welded to its side. A green arrow points to the right, where a green forged part is shown with a blue cylindrical component inserted into it, demonstrating a press fit. A target icon is located on the right side of the blue background.

Switch from a “welded brake bracket” to a forged part with press fit



The diagram shows four views of a complex mechanical assembly. The first view on the left is a perspective view of the assembly. The second view is a close-up of a specific part with a yellow arrow pointing to a detail. The third view is a wireframe model of the assembly. The fourth view is a solid model of the assembly. A target icon is located on the right side of the blue background.

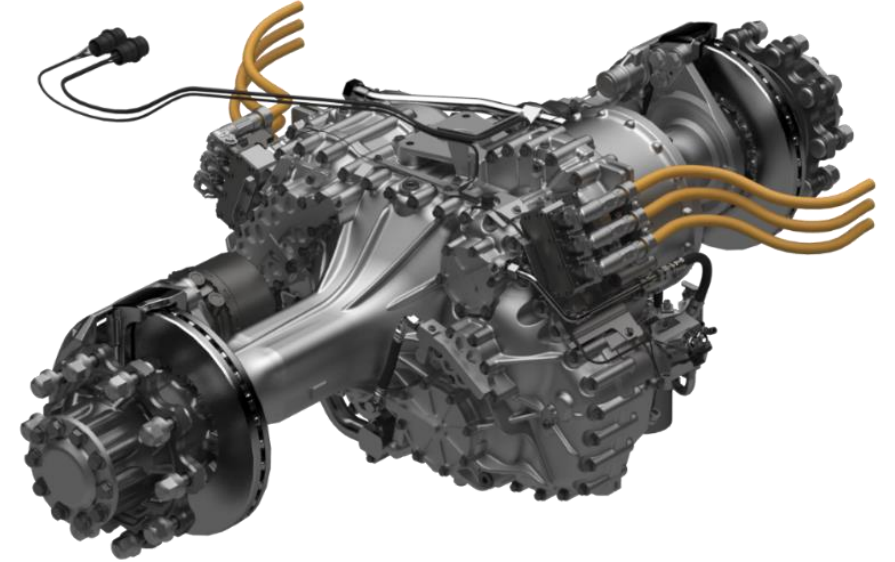
Detail adaptations for cheaper and more reliable machining

AVL HD e-Axle Development Adaptations for Production



Conclusion and Summary

- ✓ AVL has the experience for development of e-axles fulfilling all relevant series requirements
- ✓ Simulation based approach leads an optimized arrangement for the e-axle
- ✓ The chosen topology with 2 oil cooled e-motors and multi-speed transmission enables flexible operating strategies to balance efficiency and durability
- ✓ The flexible and modular concept can be adapted for various applications with different boundary conditions
- ✓ Virtual and physical testing proved the capability of the AVL HD e-axle for the application in commercial vehicles
- ✓ **The gained know-how and the individual technology building blocks can be applied to all future projects**





Q&A

Contact



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Thank you



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